

# Algorithms for computing efficient, electric-propulsion, spiralling trajectories

Completed Technology Project (2012 - 2013)



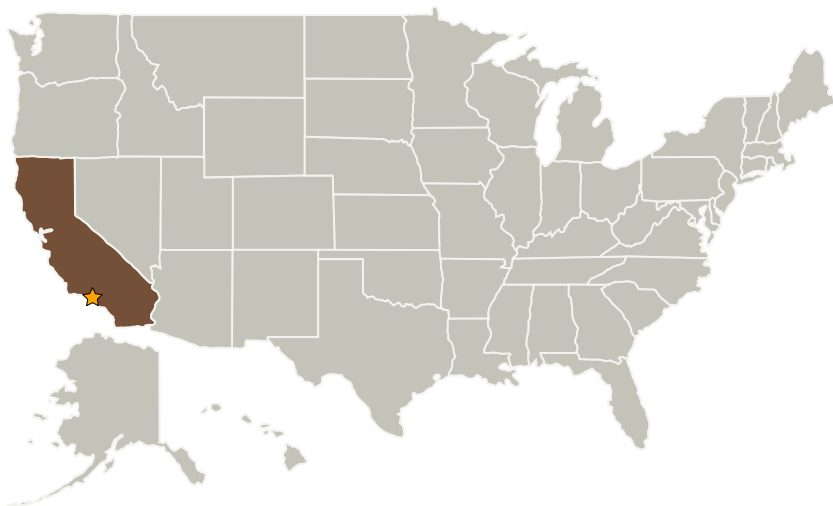
## Project Introduction

Develop techniques for rapidly designing many-revolution, electric-propulsion, spiralling trajectories, including the effects of shadowing, gravity harmonics, and possibly impulsive manoeuvres, aerodynamic effects and gravity assists.

## Anticipated Benefits

Missions will benefit from new techniques for rapidly designing many-revolution, electric-propulsion, spiralling trajectories, including the effects of shadowing, gravity harmonics, and possibly impulsive manoeuvres, aerodynamic effects and gravity assists.

## Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Type	Location
★ Jet Propulsion Laboratory (JPL)	Lead Organization	NASA Center	Pasadena, California

### Primary U.S. Work Locations

California



Algorithms for computing efficient, electric-propulsion, spiralling trajectories

## Table of Contents

Project Introduction	1
Anticipated Benefits	1
Primary U.S. Work Locations and Key Partners	1
Organizational Responsibility	1
Project Management	2
Technology Maturity (TRL)	2
Technology Areas	2

## Organizational Responsibility

### Responsible Mission Directorate:

Mission Support Directorate (MSD)

### Lead Center / Facility:

Jet Propulsion Laboratory (JPL)

### Responsible Program:

Center Independent Research & Development: JPL IRAD

# Algorithms for computing efficient, electric-propulsion, spiralling trajectories

Completed Technology Project (2012 - 2013)



## Project Management

### Program Manager:

Fred Y Hadaegh

### Project Manager:

Jonas Zmuidzinas

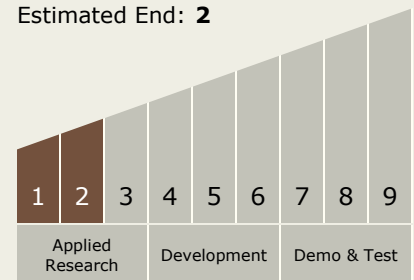
### Principal Investigator:

Anastassios E Petropoulos

## Technology Maturity (TRL)

Start: **1**

Estimated End: **2**



## Technology Areas

### Primary:

- TX17 Guidance, Navigation, and Control (GN&C)
  - └ TX17.2 Navigation Technologies
    - └ TX17.2.6 Rendezvous, Proximity Operations, and Capture Trajectory Design and Orbit Determination